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# 2018 Red Eagle International Design Competition

Icarus

Cerritos High School | California State University, Long Beach

#### **Mission Objective**

To design a lander capable of carrying a 10 metric ton payload (and crew) to the surface of Mars built and launched by 2026, to provide crucial information for exploration/development on Mars, to recapture the interest of the public for space exploration/research.

#### **System Overview**

#### • Primary Systems

• Lander, Fuel, Engines, Payload

#### Sub-systems

 Power Systems, Navigation Computer, Communications, Reaction Control System

#### Protection

• Heating, Micrometeorite, Radiation

# **Primary Systems**

#### The Icarus

- 85 ft (25.9 m) tall
- 29.52 ft (9 m) diameter
- Payload Bay Volume: 413 m<sup>3</sup>



# **Engine Considerations**

Vikas-4B	RLI0B-2	Merlin ID	Raptor

# **Engine Considerations (cont.)**

Engine	Vikas 4B	RLI0B-2	Merlin ID	Raptor
Fuel	UH25	Liquid Hydrogen	RP-I	Liquid Methane
Oxidizer	N2O4	LOX	LOX	LOX
Specific Impulse/ISP (sec)	296.2	465.5	275	334

### **Propellent Types**

UH25 + N <sub>2</sub> O <sub>4</sub>	LH <sub>2</sub> +LOX	RP-I+LOX	Liquid Methane +LOX
Fuels stable at room temperature	Highly efficient engine	Oxidizer "super-chilled": O <sub>2</sub> : -340°C	Engine not tested yet
Hypergolic	Propellants must remain liquid: H <sub>2</sub> : -259°C to	(Increases fuel efficiency)	
Deadly if inhaled or ingested	-252°C O <sub>2</sub> : -218°C to -182°C	Propellent degrades over time	

#### **Engine Considerations (cont.)**

Engine	Vik-4B	RLI0B-2	Merlin ID	Raptor
Mass (kg)	900	301	470	N/A
Thrust (N)	805,000	110,000	934,000	3,050,000 (predicted)
Thrust-to- mass Ratio	894	365	1990	N/A

# Engine Comparisons (cont.)

Engine	Vikas-4B	RLI0B-2	Merlin ID	Raptor
# of	Min: I	Min: 2	Min: I	N/A
Engines	Optimal: 3	Optimal: 4	Optimal: 3	

# Engine Configuration

#### • 3 Vikas 4B Vacuum Engines

- Triangular pattern
- All engines capable of gimbaling



# Sub-Systems

#### **Terrain-Relative**

#### Navigation

- I. Will use system comparable to Mars 2020 Rover
- 2. Will use onboard Synthetic-aperture radar to map ground
- 3. Will use an array of sensors to get variables such as velocity, drag, temperature, and attitude.
- 4. Will then use these variables to calculate alternative routes the lander could take
- 5. Would then divert course if necessary



#### Communication

- Will utilize a HRT440 X-Band High Rate transmitter
- Is able to transmit a minimum of 25 KBPS of data at a frequency of 8200.5 MHz
- Three antennas would be present
- Would use MRO as relay to Earth

HF Band	3 to 30 MHz	
/HF Band	30 to 300 MHz	
JHF Band	300 to 1000 MHz	
L Band	1 to 2 GHz	
S Band	2 to 4 GHz	
C Band	4 to 8 GHz	
X Band	8 to 12 GHz	
Ku Band	12 to 18 GHz	
K Band	12 to 27 GHz	
Ka Band	27 to 40 GHz	

#### **Reaction Control System**

- I8 R-4D thrusters in the same configuration as the Dragon Capsule
- Fuel flow rate: 0.0531 Kg/sec
- 35 Kg fuel stored in four Tanks
- Dry mass of 97.5 Kg



#### Power

- 5 Lithium Sulfur batteries providing a total of 125 Kwh storage capacity
- 2 Megaflex solar arrays each with a diameter of 5.5 m
- Will provide approximately
  25 Kw of power at Martian
  SOI





#### **Power Breakdown**

Function	Notes	Amount
Communication Systems	Radio receivers and transmitters	40 Watts
Life Support Systems	Thermal protection, lighting, hygiene, etc	17 Kilowatts
Spacecraft Control Systems	RCS thrusters, sensors	2 Kilowatts
TRN Equipment	SAR cameras, sensors	I.5 Kilowatts
Misc	Onboard computer systems	I.6 Kilowatts



#### **Heat Shield**

- The craft will have PICA (Phenolic Impregnated Carbon Ablator)-X Heat Tiles
  - Produced by SpaceX
  - Can experience temperature of up to 1,600 degrees C



#### **Heat Protection**

#### • Space Shuttle's Heat Blankets

- $\circ$  Lined inside craft
- Absorbs heat
- Can endure 3000°F (1650°C)



#### **Micrometeorite Protection**



#### **Radiation Protection**

- 4 cm of water around payload bay (28.5% decrease in radiation exposure)
- Reduces radiation exposure to 180 mSv for 6 month trip.
- Craft will rotate to facilitate temperature control



**Figure 1**. Point estimates of 5-cm depth dose for GCR at Solar Minimum as a function of areal density for various materials (<u>figure1.jpg</u>). (<u>Simonsen et al. 1997</u>)



#### Mass Breakdown (Primary

#### Svetome) Notes Mass Item Lander Aluminum-Lithium Alloy 11,680 kg Fuel UH-25 and $N_2O_4$ 76,000 kg 2,700 kg **Rocket Engines** 3 Vacuum Vikas-4B Engines Payload 10,000 kg 10 metric ton payload

#### Total: 100,000 kg

#### Mass Breakdown (Sub-systems)

ltem	Notes	Mass
Power	Solar arrays and batteries	450 kg
Terrain Navigation System	Multiple radar cameras and systems	200 kg
Communication Systems	Multiple antenna and systems	130 kg
Reaction Control System	18 R-4D Thrusters	130 kg

Total: 910 kg

#### Mass Breakdown (Protection)

ltem	Notes	Mass
Radiation protection	Water	9,700 kg
Heat Shielding	Heat blankets and PICA-X tiles	3,000 kg
Micrometeorite Protection	2 Aluminium Plates, Kevlar, Nextel, and MLI	110 kg

Total: 12,800 kg

#### **Total Mass Breakdown**

System	Mass
Primary Systems	100,380 kg
Sub-Systems	910 kg
Protection Systems	12,810 kg

# Total: 114,000 kg

### **Build Schedule**

#### Schedule

			Timeline (each rectangle is one month)	
	Start Date	End Date		
Icarus	Aug 26, 2018	Dec 31, 2026		
Planning and Design	Sep 1, 2018	Apr 9, 2019		
Tech Development	Dec 5, 2018	Jan 17, 2024		
Tech Testing	Jan 10, 2020	May 16, 2025		
Spacecraft Production	Feb 21, 2023	Apr 10, 2025		
Spacecraft Testing	Mar 26, 2024	Jun 15, 2026		
Final Preparations	Jul 15, 2026	Dec 30, 2026		

# **Mission Debrief**

- I. Aerobraking
- 2. Re-entry
- 3. Powered Descent
- 4. Landing

# Aerobrakin

#### Why Aerobraking?

- This strategy saves us about 115,000 kg worth of fuel, decreasing our mass by 52%.
- It also has a surprisingly minimal g-load on the crew, the max deceleration they will experience will be less than 10% of one g.



#### **Aerobraking Numbers**

- Periapsis velocity at **98.7** km is 5.79 **km/s** while the craft is still on its hyperbolic trajectory.
- Delta v brake from aerobraking is 2.29 km/s
- This brings the craft to an orbital velocity of 3.50 km/s.
- The extra 200 m/s of delta v gives us about 9% margin for error.

#### Aerobraking

- We also chose to put the lcarus in a 90 degree (polar) orbit. This means that the delta v calculations will be the most accurate.
- Also, this way the lcarus or any future craft will be able to choose any part of Mars to land on.









Horizontal Distance Traveled (m)

#### Landing Area

- Hellas Planitia
  - Has thickest atmosphere of Mars at over 10 millibars
  - Is relatively warm compared to rest of Mars
  - May have glaciers underneath surface
  - $\circ$   $\,$  Allows lander more time to aerobrake  $\,$
  - Has accessible lava tubes which may provide habitation for astronauts



#### **Options to Descend**

Parachute	Airbags	Powered Descent
	<image/>	

#### **Options to Descend (cont.)**

Airbags

#### Parachute

- Air too thin
- Not enough deceleration

- Causes stress on human crew
- Expensive, a lot of labor
- Optimal
- Slows down in enough time

**Powered Descent** 

#### **Cost Breakdown**

Advanced Mission Cost Model

Lander Cost

# Cost of the Lander **<u>FY 2026:</u> \$127,000,000,000**

#### System Cost = $\alpha Q^{\beta} M^{\Xi} \delta^{S} \epsilon^{(1/(IOC-1900))} B^{\phi} \gamma^{D}$

Variable:	Value Given:	Value
Q (Quantity)	Number if engineering development units, mock-ups, simulators, ground-test articles, flight test articles, and production vehicles	6
M (Mass)	Dry mass of vehicle in lbs	84,000 lb
S (Specification)	Constant for a planetary lander	2.46
IOC (Initial Operating Capability)	The system's first year of operation	2027
B (Block)	Level of design inheritance	I
D (Difficulty)	Between -2.5 to 2.5 on increments of 0.5 (-2.5 being easy and 2.5 being extremely difficult)	2.5

#### **Cost Breakdown**

ltem	Cost
Lander	\$I27 B
Fuel	\$1.3 M
Rocket Engines	\$30 M

#### Total: \$127 B

#### Summary

- Mass of Lander: 114,000 kg
- Many parts are proven successful
  - Several key parts are used on missions prior to launch in 2026
    - Mars 2020 for Terrain Relative Navigation
    - Polar Satellite Launch Vehicle for VIKAS-4B
- Few moving parts
  - $\circ$  Aerobraking
  - $\circ$  Powered descent
- Cost: \$127 B
- Able to create working production model within 8 years



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